Arduino Shield for an Induction Motor

Dr.B.Tharani¹ Mohammed Sudir S², Muthu Gokul M³, Priyadarshan M S⁴, Surya Sankar S P⁵ ¹ Professor, ^{2,3,4,5} Student, Department of Electrical and Electronics Engineering, Sri Shakthi Institute of Engineering and Technology, Coimbatore, Tamil Nadu, India.

Abstract—the induction motor stands as the most extensively utilized motor in industry, yet its faults can cause breakdowns and significant expenses. This project proposes a cost-effective system to address these issues. The idea of ours is to create a induction motor protection because induction motor is now mainly used in most of the industries and the cost of servicing of the motor is also too high for this we had try to overcome these issue we're going to prevent this from causing any damages to the motor. This will help us to bring longer life to the motor and didn't cause any severe damages to the motor.Overall, this project contributes is helpful for industries by offering a cost effective method of addressing the issue related to the motor and give not only the longer life to the motor and it will helpful for the users to reduces the expense of servicing it.

I. INTRODUCTION

The induction motor serves as an indispensable component across various industrial sectors due to its reliability, efficiency, and versatility. Its simple construction, coupled with robust performance, makes it the motor of choice for a wide range of applications, from powering conveyor belts in manufacturing plants to driving pumps in water treatment facilities. However, despite its widespread use, induction motors are not immune to faults and failures. Problems such as bearing wear, winding insulation degradation, and rotor imbalance can lead to unexpected downtime, production losses, and increased maintenance costs for industries. Addressing these issues promptly and effectively is crucial to ensure uninterrupted operation and maximize productivity. Therefore, there is a pressing need to develop cost-effective solutions that can detect and mitigate faults in induction motors, minimizing downtime and optimizing operational efficiency for industries reliant on these vital machines. The Induction Motor Protection System project aims to enhance the reliability and longevity of induction motors by implementing a comprehensive monitoring and control system. By integrating sensors to detect parameters such as temperature, vibration, and RPM, the project ensures real-time monitoring of the motor's operating conditions. In the event of any anomalies or factors indicating potential faults beyond acceptable limits, the system initiates automatic shutdown using a relay mechanism, preventing further damage and mitigating risks of breakdowns. This proactive approach to motor protection not only minimizes downtime and maintenance costs but also enhances overall operational efficiency by ensuring uninterrupted performance of critical industrial processes.

II. LITERATURE REVIEW

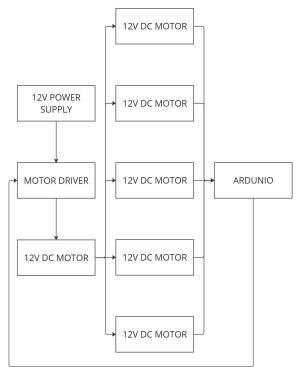
The literature review presents an overview of different studies related to the Induction motor protection system.Study focus on the accurate determination of Induction motor protection system and the development of systems. This comprehensive literature review delves into the advancements made in protective measures for both single-phase and three-phase induction motors within industrial contexts. The primary focus centers on the development and implementation of innovative approaches aimed at enhancing motor safety, efficiency, and overall operational reliability. The first explored method introduces a microcontroller-based system utilizing Atmega16 for safeguarding single-phase motors. This system not only incorporates traditional overload and short circuit protection but also introduces a pioneering no-load safeguard, a feature typically absent in commercially available motor protection devices. Leveraging the microcontroller's capabilities enables the customization of parameters, such as upper and lower current limits, providing flexibility for field engineers. Moreover, real-time monitoring of variable site parameters (VSPs) and operational events, including load currents, is facilitated through an interfaced LCD display, enhancing control precision and responsiveness. Moving to three-phase motor protection, the second approach adopts a networked model for fault prevention and remote control within industrial plants. This system is designed to detect a multitude of faults, including incorrect phase sequences, overload and no-load currents, surge voltages, phase imbalances, and single phasing. Through the implementation of TCP/IP protocol over LAN, measured electrical parameters, fault conditions, and motor performance statuses are seamlessly transmitted to a centralized monitoring system. This centralized monitoring system not only enables remote operation and monitoring of multiple motor modules but also provides a user-friendly interface for proactive maintenance, performance optimization, and comprehensive record-keeping from remote stations. Together, these reviewed studies highlight the critical role of advanced monitoring and control systems in ensuring equipment safety, optimizing industrial processes, and fostering operational efficiency in manufacturing industries.

III. METHODOLOGY

The Induction Motor Protection system using Arduino represents a groundbreaking advancement in the realm of motor monitoring and control, offering a comprehensive array of functionalities aimed at ensuring the optimal performance and longevity of induction motors across diverse industrial applications. At its core, this innovative system comprises a sophisticated network of sensors meticulously designed to capture and analyze critical motor parameters in real-time. These sensors include infrared (IR), vibration, temperature, current, and voltage sensors, strategically deployed to provide a holistic view of motor health and operation. Working in tandem with essential components such as a motor driver, a 12V DC motor, and the Arduino Uno microcontroller board, this system forms a robust framework for continuous monitoring and adaptive control. The temperature sensor diligently tracks variations in motor temperature, offering invaluable insights into thermal management and potential overheating risks. Meanwhile, the vibration sensor meticulously detects and quantifies motor vibrations, serving as an early warning system for mechanical faults and imbalances. The IR sensor plays a pivotal role in monitoring motor speed (RPM), facilitating precise control and performance optimization. Additionally, the current and voltage sensors meticulously measure electrical parameters such as amperage and input voltage, enabling comprehensive analysis of motor power consumption and supply integrity. The collected data is then relayed to the Arduino Uno, where sophisticated algorithms and predefined thresholds are employed to assess motor health and trigger appropriate control actions. In the event of parameter deviations exceeding safety thresholds, the Arduino Uno swiftly communicates with the motor driver to initiate corrective measures, including motor shutdown if necessary, thus preempting potential damage and hazards. This robust system not only ensures efficient motor monitoring but also empowers industries with proactive maintenance capabilities, ultimately leading to extended motor lifespan and enhanced operational reliability. With its versatility, precision, and adaptability, the Induction Motor Protection system using Arduino represents a paradigm shift in motor management practices, offering unparalleled benefits to a wide range of industrial sectors reliant on induction motor-driven machinery.

IV. PROPOSED SYSTEM

The proposed system stands as an ambitious testament to innovation in motor monitoring and protection, embarking on a monumental quest to fortify the performance and endurance of induction motors within the sprawling expanse of industrial domains. Its overarching mission radiates a steadfast commitment to perpetual vigilance over a pantheon of pivotal motor parameters, spanning the realms of temperature, vibration, RPM, current, and input voltage, thus preemptively erecting a bastion against the specter of potential faults and imperfections, while championing a relentless pursuit of operational excellence. This Herculean endeavor finds its fulcrum in an intricate tapestry of cutting-edge sensor technologies, an ensemble cast comprising the formidable prowess of infrared (IR), vibration, temperature, current, and voltage sensors, meticulously choreographed to capture and dissect every nuanced facet of motor behavior, bequeathing unto the system a veritable treasure trove of real-time data ripe for relentless scrutiny and meticulous analysis. Empowered by the computational eminence of the Arduino Uno microcontroller, the system metamorphoses into an omniscient sentinel, endowed with the sagacity to instantaneously parse sensor outputs, thus engendering swift, incisive responses to even the most infinitesimal deviations from the hallowed corridors of prescribed operating thresholds. Yet, its zenith of efficacy lies enshrined within the hallowed precincts of threshold-based control paradigms, wherein meticulously delineated thresholds for each parameter bestow upon the Arduino Uno the hallowed mantle of stewardship, orchestrating with unparalleled acumen the symphony of motor activation or deactivation, orchestrated by the symphonic crescendo of sensor-derived insights. This indomitable ethos not merely safeguards the motor's sanctity but also serves as an impervious bulwark against the encroaching tempests of costly downtime, poised to quell motor operations at the merest whisper of aberration. Moreover, in its all-encompassing embrace of the kaleidoscopic exigencies that pervade the industrial landscape, the system emerges as an undulating beacon of adaptability and versatility, an ardent vanguard steadfastly propelling operational reliability and productivity to celestial realms across the industrious continuum. In summation, through its resolute vigilance and unwavering fortifications, the proposed system heralds a seismic epoch in motor management, unfurling a glorious pantheon of benefits poised to transmute the very fabric of industrial ingenuity and resilience into an indelible testament to human innovation.



V. BLOCK DIAGRAM FOR PROPOSED SYSTEM

Figure Block diagram of induction motor protection using arduino

Specification

- Operating Voltage: 4 V to 30 V
- Output Voltage: 10mV/°C
- Sensitivity: 10mV/°C
- Linearity Error: ±1°C (for 0°C to +100°C)
- Operating Temperature: -55°C to +150°C
- Output Impedance: 100Ω
- Power Consumption: 60 µA (typical)
- Package Type: TO-92, TO-220, SOIC
- Output Type: Analog
- Accuracy: ±1°C (typical)

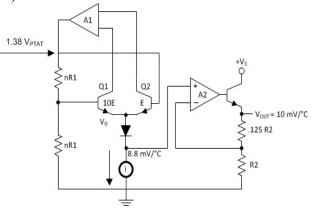


Figure Block diagram of temperature sensor

IR SENSOR

Volume 24 Issue 1 March 2024

Infrared Obstacle Avoidance IR Sensor Module (Active Low) has a pair of infrared transmitting and receiving tubes. When the transmitted light waves are reflected back, the reflected IR waves will be received by the receiver tube. The onboard comparator circuits does the processing and the green indicator LED comes to life. The module features a 3 wire interface with Vcc, GND, and an OUTPUT pin on its tail. It works fine with 3.3 to 5V levels. Upon hindrance/reflectance, the output pin gives out a digital signal (a low-level signal).

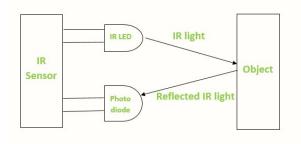


Figure Block diagram of IR Sensor

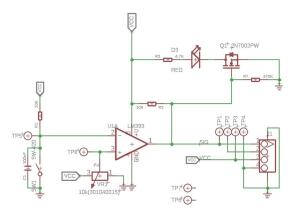
Specification

- Board Size-3.2 x 1.4cm
- Working voltage 3.3 to 5V DC
- Operating voltage-3.3V: ~23 mA, to 5V: ~43 mA
- Detection range-2cm 30cm
- Active output level
- The output is "0" (Low) when an obstacle is detected

VIBRATION SENSOR

Single-roller type full induction trigger switch. When no vibration or tilt, the product is ON conduction state, and in the steady state, when a vibration or tilt, the switch will be rendered instantly disconnecting the conductive resistance increases, generating a current pulse signal, thereby triggering circuit. These products are completely sealed, waterproof, and dustproof. This sensor module produces logic states depending on vibration and external force applied on it. When there is no vibration this module gives logic LOW output. When it feels vibration then output of this module goes to logic HIGH. The working bias of this circuit is between 3.3V to 5V DC. Connect Vcc pin of sensor board to 5V pin of Arduino board, connect Gnd pin to Gnd pin of Arduino, Connect DO output signal pin of sensor board to Arduino digital pin D3. Do some calibration and adjust the sensitivity threshold, then upload the following sketch to the Arduino board.

ACS712 CURRENT SENSOR



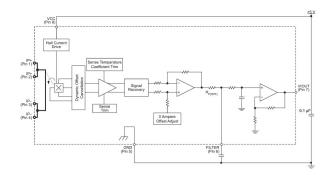


Figure: Block diagram of Current sensor

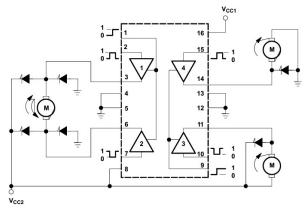


Figure 6.7: Block diagram of Motor Driver

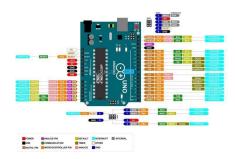
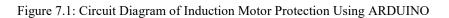
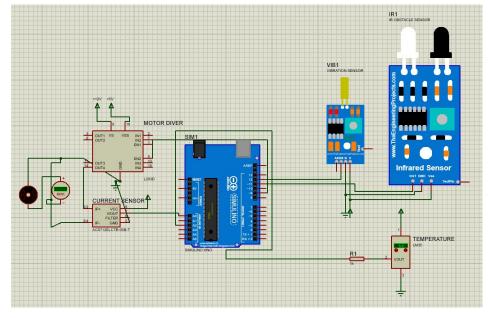


Figure : Arduino UNO IMPLEMENTATION AND WORKING

Circuit Diagram



VI. WORKING



The proposed Induction Motor Protection system utilizing Arduino aims to enhance motor reliability by monitoring critical parameters such as temperature, vibration, RPM, current, and input voltage. This system employs a combination of sensors and a microcontroller to ensure efficient monitoring and protection of the induction motor.

VII. RESULT ANALYSIS AND DISCUSSIONS

- 1. Sensor Integration: The temperature sensor tracks motor temperature to prevent overheating. The vibration sensor measures motor vibration, indicating potential issues such as imbalance or misalignment. The IR sensor detects motor RPM, providing insights into motor speed and performance.
- 2. Arduino Code: A program is developed using the Arduino IDE to read the analog/digital signal from the sensors. This signal varies based on the condition of the motor.
- 3. Sensors Interpretation: The Arduino reads the analog/digital value from the sensors, which corresponds to the motor. If the value falls below a predetermined threshold level, it indicates that there needs to be a change in output to the motor driver.
- 4. Automated Turning Off: If automated turning of the motor is implemented, the Arduino can deactivate the motor using the motor driver. The motor can be turned off using the motor driver.
- 5. Monitoring and Adjustment: Monitoring the Serial Monitor output allows users to observe sensor readings and system responses. Sensor thresholds and turning off the motor can be based on the specific condition of the motor.

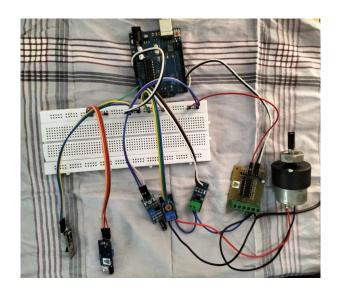


Figure: Hardware Output IV. CONCLUSION

In conclusion, the Induction Motor Protection system utilizing Arduino presents a comprehensive and effective solution for monitoring and safeguarding critical motor parameters in industrial settings. This project offers significant benefits, including prolonged motor lifespan, enhanced operational efficiency, and improved safety across various industries reliant on induction motors. Moving forward, further enhancements and refinements to this system could lead to even greater reliability and performance, solidifying its position as a valuable tool in ensuring the smooth operation of industrial processes.

REFERENCES

- [1] R. Santhosh, V. S. M, Sailakshmi and S. Yadav, "Hardware Design of Network Model of Protection and Controller module for Three-Phase Induction Motors in Industrial Plants with Remote Monitoring System on a Centralized System," 2022 International Conference on Innovations in Science and Technology for Sustainable Development (ICISTSD), Kollam, India, 2022, pp. 93-98, doi: 10.1109/ICISTSD55159.2022.10010403.
- V. Sharma, M. J. Hossain and S. M. N. Ali, "Fault Protection Technique for ZSI-fed Single-Phase Induction Motor Drive System," 2018 IEEE Region Ten Symposium (Tensymp), Sydney, NSW, Australia, 2018, pp. 30-35, doi: 10.1109/TENCONSpring.2018.8691986.
- [3] C.Nagarajan and M.Madheswaran 'Experimental verification and stability state space analysis of CLL-T Series Parallel Resonant Converter' - Journal of ELECTRICAL ENGINEERING, Vol.63 (6), pp.365-372, Dec.2012.
- C.Nagarajan and M.Madheswaran 'Performance Analysis of LCL-T Resonant Converter with Fuzzy/PID Using State Space Analysis'-Springer, Electrical Engineering, Vol.93 (3), pp.167-178, September 2011.
- [5] C.Nagarajan and M.Madheswaran 'Stability Analysis of Series Parallel Resonant Converter with Fuzzy Logic Controller Using State Space Techniques'- Taylor & Components and Systems, Vol.39 (8), pp.780-793, May 2011.
- [6] C.Nagarajan and M.Madheswaran 'Experimental Study and steady state stability analysis of CLL-T Series Parallel Resonant Converter with Fuzzy controller using State Space Analysis'- Iranian Journal of Electrical & Comparison (2012), September 2012.
- [7] Nagarajan C., Neelakrishnan G., Akila P., Fathima U., Sneha S. "Performance Analysis and Implementation of 89C51 Controller Based Solar Tracking System with Boost Converter" Journal of VLSI Design Tools & Technology. 2022; 12(2): 34–41p.
- [8] C. Nagarajan, G.Neelakrishnan, R. Janani, S.Maithili, G. Ramya "Investigation on Fault Analysis for Power Transformers Using Adaptive Differential Relay" Asian Journal of Electrical Science, Vol.11 No.1, pp: 1-8, 2022.
- [9] G.Neelakrishnan, K.Anandhakumar, A.Prathap, S.Prakash "Performance Estimation of cascaded h-bridge MLI for HEV using SVPWM" Suraj Punj Journal for Multidisciplinary Research, 2021, Volume 11, Issue 4, pp:750-756
- [10] G.Neelakrishnan, S.N.Pruthika, P.T.Shalini, S.Soniya, "Perfromance Investigation of T-Source Inverter fed with Solar Cell" Suraj Punj Journal for Multidisciplinary Research, 2021, Volume 11, Issue 4, pp:744-749
- [11] C.Nagarajan and M.Madheswaran, "Analysis and Simulation of LCL Series Resonant Full Bridge Converter Using PWM Technique with Load Independent Operation" has been presented in ICTES'08, a IEEE / IET International Conference organized by M.G.R.University, Chennai.Vol.no.1, pp.190-195, Dec.2007

- [12] M Suganthi, N Ramesh, "Treatment of water using natural zeolite as membrane filter", Journal of Environmental Protection and Ecology, Volume 23, Issue 2, pp: 520-530,2022
 - [13] M Suganthi, N Ramesh, CT Sivakumar, K Vidhya, "Physiochemical Analysis of Ground Water used for Domestic needs in the Area of Perundurai in Erode District", International Research Journal of Multidisciplinary Technovation, pp: 630-635, 2019
 - [14] R. Santhosh, Sailakshmi, V. S. M, S. Yadav, N. M and
 - [15] S. P, "No-Load and Over Load Protection for Single Phase Induction Motors," 2021 2nd International Conference on Smart Electronics and Communication (ICOSEC), Trichy, India, 2021, pp. 462-466, doi: 10.1109/ICOSEC51865.2021.9591938.
 - [16] T. Dimova, "Investigation of Digital Protection Relay For Three-Phase Induction Motor," 2021 17th Conference on Electrical Machines, Drives and Power Systems (ELMA), Sofia, Bulgaria, 2021, pp. 1-4, doi: 10.1109/ELMA52514.2021.9503040.
 - [17] N. de Jesús Orozco Morales, E. C. Quispe, J. R. Gómez Sarduy and P. R. Viego Felipe, "Set Point of the Thermal Overload Protection of Large Induction Motors by Simulated Testing," 2022 IEEE ANDESCON, Barranquilla, Colombia, 2022, pp. 1-5, doi: 10.1109/ANDESCON56260.2022.9989526.