

Automatic Pick And Drop Helping Robot

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Abstract: In the present pandemic situation constant monitoring of patient's body parameters such as temperature, pulse rate and oxygen level etc. becomes difficult to nurses. Hence to overcome this we implemented a robot which can monitor and assist the patient using Robotic Arm. In our paper we are monitoring pulse rate, oxygen level and temperature of the patient by using respective sensors and also with the help of camera capturing live image or video of the patient and can be monitored continuously. If any changes in patient's physical conditions it will be uploaded to cloud and alerts monitoring person through SMS. Here the robot can assist the patients by supplying medications, juice & fruits using Robotic Arm. By using BLUEDOT app the wheels can be moved to RIGHT, LEFT, FORWARD & BACKWARD and the robotic arm in the developed system has five Degree of Freedom (DOF), to operate this robot arm MIT inventor app is used. Hence it removes the problem of monitoring the patients suffering from communicable diseases.

Keywords: Robotic Arm, Temperature sensor, pulse sensor, Arduino UNO

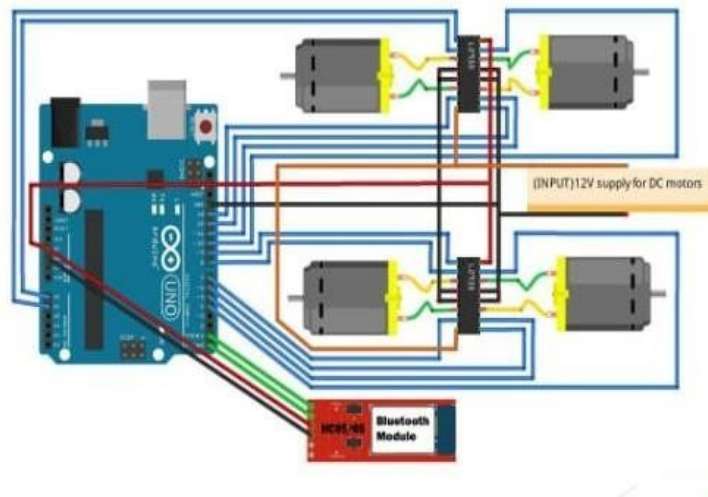
I. INTRODUCTION

As the technology is improving day by day, life span of people is also increasing gradually which leads to the population increase; it became a necessity to monitor the patient's health conditions of people for their healthy lifestyle. Improving health care has become one of the most important factors in medical industry. Without quality monitoring it is impossible to monitor the conditions of patients, though there are millions of medical centers across the world. It's difficult there to provide attention to each and every patient, especially patients who are suffering from communicable diseases like Covid-19, Hepatitis B. It is practically very difficult to monitor the conditions of those patients because of fear of infection. According to recently conducted survey 122 per 100,000 die because of lack of attention during their bedridden time. Thus patient assistance and monitoring becomes an important thing to meet the objective. Achieving patient satisfaction. So the current method of providing assistance and monitoring patient is not satisfied, Hence medical industry is looking for new advancement in technology to overcome the above mentioned problem. Our paper proposes a Robot which continuously monitors the conditions of patients and thus became advancement in medical industry. Health is the one of the global challenges for humanity. Recently, the patient monitoring systems is one of the major advancements because of its advanced technology. In the traditional approach they need to visit the patient's ward for checking Active hospitals.

II. PROPOSED WORK

In this methodology section, it contains two parts such as hardware and software requirements. Where all the parts are assembled to accomplish the function of monitoring and assistance task. Our proposed Robotic system is designed to perform task based on the instructions provided by the person who is controlling the system in this paper, we are using Raspberry pi 3 module for the communication between the robot and the monitoring person. Robot are connected with the motors, driven by the L298 Motor drivers which in turn, drives the wheels of our proposed Robot, operated by Android app known as Blue dot with the established Bluetooth connection with raspberry pi module. Initially the Robot starts to move, Pi camera which is connected to the raspberry pi module used to capture live streaming of the surroundings. Sensors such as MLX90614 used for contactless temperature measurement of the patient, MAX30102 Finger pulse sensor which is connected to Arduino UNO for analog to digital conversion are used for measuring Pulse rate, oximetry of the patient respectively.

Fig.1.Block Diagram



III. HARDWARE REQUIREMENTS

DC engine as displayed in the beneath figure utilizes Direct Current to create mechanical rotational development. At the point when it changes over electrical energy into mechanical energy then it is called as DC engine and when it changes over mechanical energy into electrical energy then it is called as DC generator. The functioning standard of DC engine is relies upon the way that when a current conveying conductor is set in an attractive field, it encounters a mechanical power. Its revolution bearing relies upon Fleming's Left Hand Rule. The figure shows dc engine which is utilized to make development. In this system, two dc motors are used which can be driven by motor driver module.

Motor Drive Module:

PI cannot drives the dc engine straight forwardly. The current and voltage esteems are not coordinated with regulator and dc engines. So engine driver is given to drive the engine. The L298N displayed in figure 4 is an incorporated single circuit in a 15 lead multi watt and Power bundles. Due to its a high ebb and flow, high voltage with double full-connect driver which is intended to acknowledge standard TTL rationale level sand drive inductive loads like DC, venturing engines, transfers, solenoids. Two empower inputs are given to dynamic or de active the gadget autonomously. In each extension the producers of the lower semiconductors are associated together and the individual outer terminal can likewise be utilized for the association of an outside detecting resistor. Supply input is likewise given to that, so the rationale works at a lower voltage.

Arduino UNO:

Arduino UNO is here used as analog to digital coverts since Raspberry capable of accepting only digital inputs. It is belonging to the mega processor family.

Fig.2. Arduino UNO

It has 6 analog inputs and 14 digital pins works at the frequency of 16 Mhz. It consists of a power jack, USB connection and a reset button. It can able to read the input whenever it reads the input the light will glow in the sensor, and it sends the message then this message is become to an output.



Max 30102 pulse sensor:

It is used to measure the heartbeat of the patient. It has a programmable sample rate and LED power for power saving mode. It has -40°C to $+85^{\circ}\text{C}$ operating frequency range. This device can be turned off by software without using standby current and it is a highly sensitive device.

IV. SIMULATION RESULTS

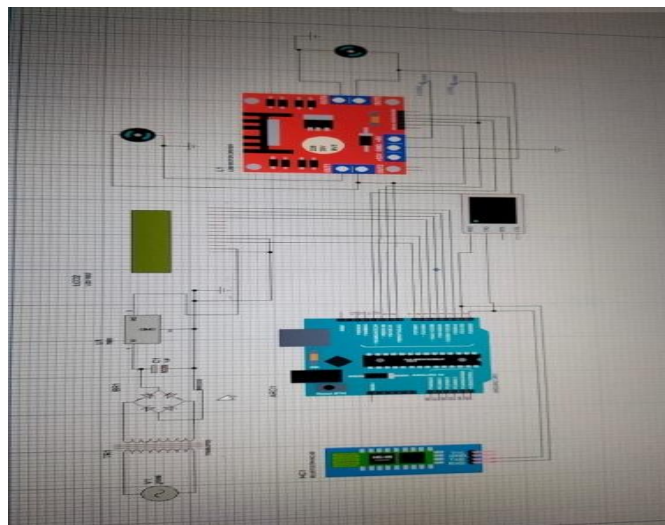


Fig.3.Simulation Result

The components like both hardware and software and hardware's are attached to it. Hardware's like Motor drive, Bluetooth module, Arduino, wheels are connected to it and C programming is used here by pressing the LEFT, RIGHT, UP, DOWN in our mobile phones. Then it can rotate and round using the instructions we are giving to the mobile phones. There are four wheels which can rotate by our instructions and the battery which works on our instructions we are giving and then it will move around every side. The experimental results for this have come very sharply with accurate precisions. We can use this by pressing the LEFT, RIGHT, UP, DOWN in our mobile phones. Then it can rotate and round using the instructions we are giving to the mobile phones. There are four wheels which can rotate by our instructions and the battery which works on our instructions we are giving and then it will move around every side.



Fig.4. Hardware Implementation

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